Collaborative behaviors for humanoid robots

In this project, you will work with two Aldebaran Naos on a multi-robot task. The goal of this project will be to develop coordination between two humanoids to carry an object from one place to another together, and possibly some other tasks that involve coordination. You will mainly focus on software development with the two humanoids.



Professor: Hadas Kress-Gazit (hadaskg@cornell.edu)
Course number: CS4999/CS5999/ MAE4900/MAE6900

Credits: 3-4

Contact: Catherine Wong (kw358@cornell.edu)